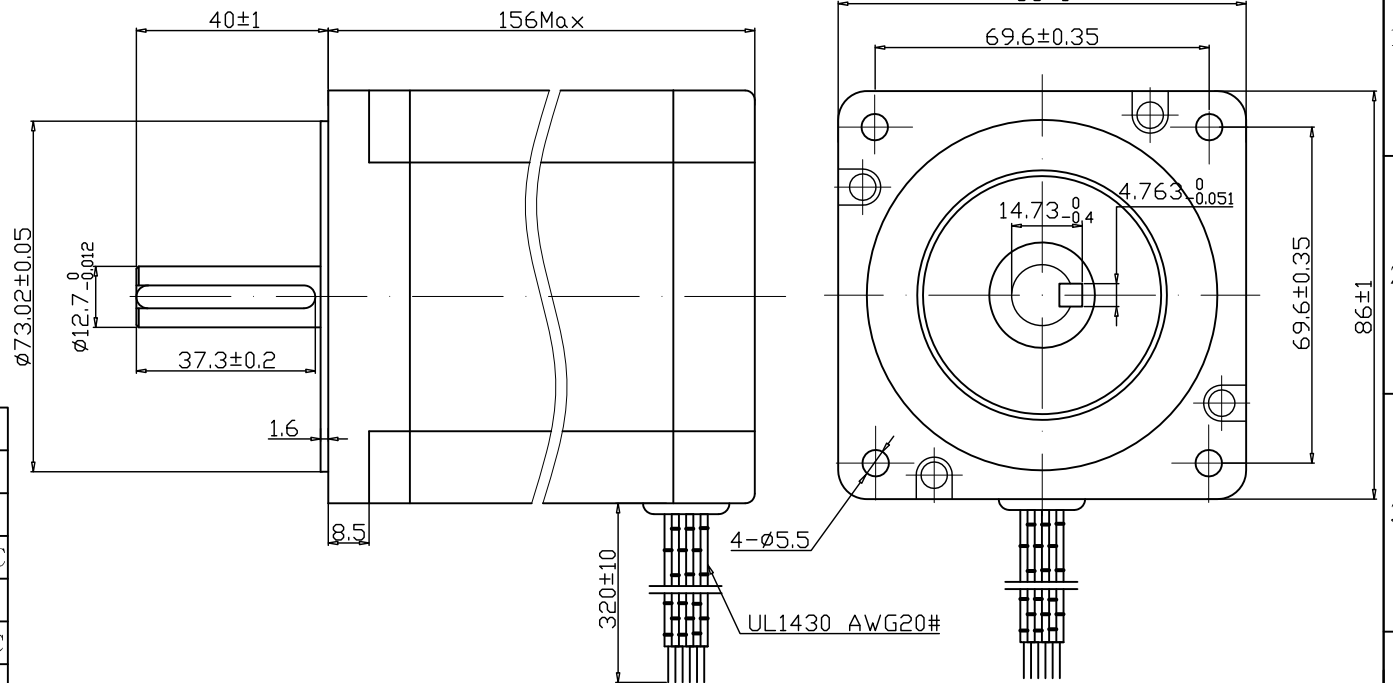
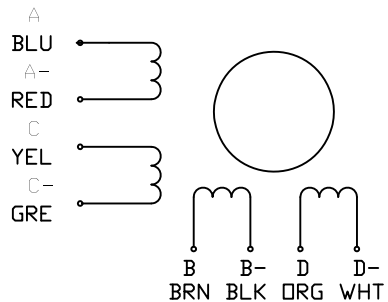


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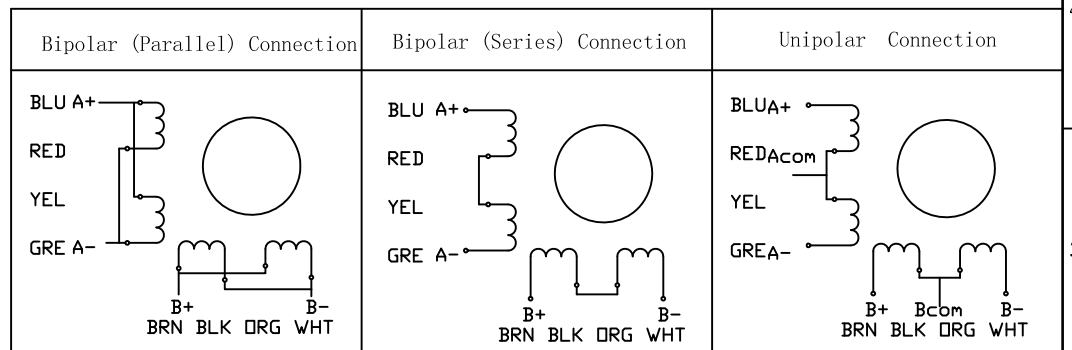
Wiring Diagram



SPECIFICATIONS

1	Number of Phase	4
2	Step Angle	1.8° ±5%
3	Rotor Inertia	5650g • cm ²
4	Insulation Resistance	100MΩ 500VDC
5	Insulation Class	B (130°C)
6	Ambient Temperature	-20°C to 50°C
7	Ambient Humidity	15% to 95%
8	Motor Weight	Approx 5.5 kg

◇WIRINGS CONNECTION DIAGRAM



	Holding Torque (2 phases on) N. cm ±10%	Rated Current/Phase (Amps DC)	Resistance/Phase (ohms) ±10%	Voltage/Phase (V DC)	Inductance/Phase (mH) ±20% Typical (1kHz)
Unipolar	900	6.2	0.75	4.65	5.5
Bipoar (Series)	1280	4.4	1.5	6.6	21
Bipoar (Parallel)	1280	8.8	0.38	3.34	5.5

Unit:mm
 First angle method
 Tolerances for linear and angular dimensions without individual tolerance indications
 GB/T 1804-m eqv ISO 2768-1:m
 Geometrical tolerances for features without individual tolerance indications
 GB/T 1184-k eqv ISO 2768-2:k

DESIGN		
CHECK		
TECHNOLOGY		
STANDARD		
APPROVE		
NAMES	SINGATURE	DATE

TYPE: HYBRID STEPPING MOTOR	SCALE XX	Rev. 2.0	SHEET 1 OF 1
Model: KL34H2160-62-8A-KEY			

REV.	REVISION RECORD	DATE	UNLESS OTHERWISE SPECIFIDE

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